CS6375: Machine Learning Gautam Kunapuli

Linear Classification: Perceptron



Example: Handwritten Digit Recognition



The United States Postal Service Zip Code Database contains 16 x 16 pixel images of scanned handwritten digits. Typical human error rate is around 2.5%.



We can reshape each 16 x 16 image matrix into a 256×1 image vector; each row is a digit, represented by its 256 (= 16×16) pixels.

Machine Learning Task: Identify digits from data automatically; that is classify each image as a digit. This is an instance of a classification task. As there are 10 digits, this is an example of a multi-class classification problem.

Example: Handwritten Digit Recognition

Alternately, we can extract two informative features from each image: intensity and symmetry. Data set is 2-dimensional.



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Problem Setup: Given data (x_i) and classification labels (y_i) , find the best model that separates/classifies current data and predicts future data

Example: Develop a model to classify between 1s and 5s.

Here, the independent variables (training data) are average intensity and symmetry of the digit images (x_i) and the dependent variable (label) is 1 or 5 (y_i) .



Our hypothesis class is the space of all **linear functions**, $y = f(x) = w^T x + b$

in this 1vs5 digit classification task, the training examples are two-dimensional (intensity, symmetry), that is $x \in \mathbb{R}^2$

In *n* dimensions, a **hyperplane** is a solution to the equation, $w^T x + b = 0$ with $w \in \mathbb{R}^n$ and $b \in \mathbb{R}$. Hyperplanes **divide** \mathbb{R}^n **into two distinct sets** of points (called open half-spaces)



For a classification problem, the labels are **not continuous**, but **nominal**. Here, denote the labels for **Digit 1 as y = +1** and the labels for **Digit 5 as y = -1**.

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Problem: Given *n* training examples (x_i, y_i) , i = 1, ..., n, where $y_i = \{+1, -1\}$, find the best model (w, b)



In linear regression, we measure fit using the squared loss over the error, that is, we use a **squared loss function**,

$$L(f(x_i), y_i) = \frac{1}{2} (y_i - (w \cdot x_i + b))^2$$

Is this still a good loss function?

Count the number of misclassifications:

$$L(f(x_i), y_i) = \frac{1}{2} |y_i - \operatorname{sign}(w \cdot x_i + b)|$$

Loss function is not differentiable, difficult to optimize

Penalize each misclassification by the size of the violation, using the modified hinge loss

$$L(f(x_i), y_i) = \max\{0, -y_i \cdot (w \cdot x_i + b)\}$$

Only misclassified points will have a loss > 0. Correctly classified points will always have loss = 0. **Why?**

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minimize $\sum_{i=1}^{n} \max \{0, -y_i \cdot (\boldsymbol{w}^T \boldsymbol{x}_i + b)\}$

This is an **(unconstrained) optimization problem** in the variables (w, b). The **optimal solution** will be our model.

Solution Approach: Solve using optimization techniques, e.g., **gradient descent**. However, the loss function is convex, but **not differentiable everywhere**!

Perceptron

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Piecewise continuous functions such as max(0, x) and |x| are not differentiable everywhere (in this case, at x = 0).



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Piecewise continuous functions such as max(0, x) and |x| are not differentiable everywhere. We compute the **sub-gradient** instead.



For a convex function f(x), a **sub-gradient** at a point x_0 is **any tangent line or plane** through the point x_0 that underestimates (supports) the function **everywhere**.

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Solution Approach 1: Solve using optimization techniques, e.g., <u>sub-</u><u>gradient</u> descent (compare with gradient descent used for regression)

Initalize: $w = w_0, b = b_0, t = 0$ Iterate until convergence Compute updates: $w_{t+1} = w_t - \eta_t \nabla_w L(f(x), y)$ $b_{t+1} = b_t - \eta_t \nabla_b L(f(x), y)$ Check for convergence Continue to next iteration: t = t + 1

$$\nabla_{w}L(f(\boldsymbol{x}_{i}), y_{i}) = \sum_{i:-y_{i}f(\boldsymbol{x}_{i})>0} -y_{i} \cdot \boldsymbol{x}_{i}$$
$$\nabla_{b}L(f(\boldsymbol{x}_{i}), y_{i}) = \sum_{i:-y_{i}f(\boldsymbol{x}_{i})>0} -y_{i}$$

gradient only depends on the misclassified examples

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Solution Approach 2: To make training more practical, <u>stochastic sub-</u> <u>gradient</u> descent is used instead of sub-gradient descent

Initalize: $w = w_0, b = b_0$ for i = 1, ..., nSelect a random training example, (x_i, y_i) Compute updates if (x_i, y_i) misclassified $w_{i+1} = w_i - \eta_i \nabla_w L(f(x_i), y_i)$ $b_{i+1} = b_i - \eta_i \nabla_b L(f(x_i), y_i)$ Else $w_{i+1} = w_i$ $b_{i+1} = b_i$

 $\nabla_{w}L(f(\boldsymbol{x}_{i}), y_{i}) = -y_{i}\boldsymbol{x}_{i}$ $\nabla_{b}L(f(\boldsymbol{x}_{i}), y_{i}) = -y_{i}$

approximate the gradient *by sampling* a few examples uniformly at random and averaging; in the extreme case, select only a single example

stochastic gradient descent **converges** under mild assumptions on the step size (it should decrease

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Drawbacks:

- No convergence guarantees if the observations are <u>not</u> linearly separable
- **Can overfit**: there can be a number of perfect classifiers, but the perceptron algorithm doesn't have any mechanism for choosing between them

$$\nabla_{w} L(f(\boldsymbol{x}_{i}), y_{i}) = -y_{i} \boldsymbol{x}_{i}$$
$$\nabla_{b} L(f(\boldsymbol{x}_{i}), y_{i}) = -y_{i}$$

Limitations of Linear Hypotheses



Classification: Linearly inseparable classes

